#### E01THF – NAG Fortran Library Routine Document

**Note.** Before using this routine, please read the Users' Note for your implementation to check the interpretation of bold italicised terms and other implementation-dependent details.

### 1 Purpose

 $\rm E01THF$  evaluates the three-dimensional interpolating function generated by  $\rm E01TGF$  and its first partial derivatives.

## 2 Specification

SUBROUTINE E01	THF(M, X, Y, Z,	F, IQ, LIQ, RQ, LRQ, N, U, V, W, Q,
1	QX, QY, QZ,	IFAIL)
real	X(M), Y(M),	Z(M), $F(M)$ , $RQ(LRQ)$ , $U(N)$ , $V(N)$ ,
1	W(N), Q(N),	QX(N), QY(N), QZ(N)
INTEGER	M, IQ(LIQ),	LIQ, LRQ, N, IFAIL

# 3 Description

This routine takes as input the interpolant Q(x, y, z) of a set of scattered data points  $(x_r, y_r, z_r, f_r)$ , for r = 1, 2, ..., m, as computed by E01TGF, and evaluates the interpolant and its first partial derivatives at the set of points  $(u_i, v_i, w_i)$ , for i = 1, 2, ..., n.

 $\rm E01THF$  must only be called after a call to  $\rm E01TGF.$ 

This routine is derived from the routine QS3GRD described by Renka [1].

### 4 References

[1] Renka R J (1988) Algorithm 661: QSHEP3D: Quadratic Shepard method for trivariate interpolation of scattered data ACM Trans. Math. Software 14 151–152

### **5** Parameters

1:	M - INTEGER	Input
2:	X(M) - real array	Input
3:	m Y(M) - real array	Input
4:	m Z(M) - real array	Input
5:	F(M) - real array	Input
	On entry: M, X, Y, Z and F must be the same values as were supplied in the preceding	call to

E01TGF. 6: IQ(LIQ) — INTEGER array Input

On entry: IQ must be unchanged from the value returned from a previous call to E01TGF.

7: LIQ — INTEGER Input On entry: the dimension of the array IQ as declared in the (sub)program from which E01THF is called.

Constraint:  $LIQ \ge 2 \times M + 1$ .

8: RQ(LRQ) - real array

On entry: RQ must be unchanged from the value returned from a previous call to E01TGF.

Input

Input

Input

Output

Input/Output

9: LRQ — INTEGER

 $On\ entry:$  the dimension of the array RQ as declared in the (sub)program from which E01THF is called.

Constraint: LRQ  $\geq 10 \times M + 7$ .

10: N — INTEGER

 $On \ entry: n$ , the number of evaluation points.

Constraint: N  $\geq$  1.

11: U(N) - real arrayInput12: V(N) - real arrayInput13: W(N) - real arrayInput14: V(N) - real arrayInput

On entry: the evaluation points  $(u_i, v_i, w_i)$ , for i = 1, 2, ..., n.

14: Q(N) - real array

On exit: the values of the interpolant at  $(u_i, v_i, w_i)$ , for i = 1, 2, ..., n. If any of these evaluation points lie outside the region of definition of the interpolant the corresponding entries in Q are set to the largest machine representable number (see X02ALF), and E01THF returns with IFAIL = 3.

15:	QX(N) - real array	Output
16:	$\operatorname{QY}(\operatorname{N})$ — <i>real</i> array	Output
17:	QZ(N) - real array	Output

On exit: the values of the partial derivatives of the interpolant Q(x, y, z) at  $(u_i, v_i, w_i)$ , for i = 1, 2, ..., n. If any of these evaluation points lie outside the region of definition of the interpolant, the corresponding entries in QX, QY and QZ are set to the largest machine representable number (see X02ALF), and E01THF returns with IFAIL = 3.

#### 18: IFAIL — INTEGER

On entry: IFAIL must be set to 0, -1 or 1. For users not familiar with this parameter (described in Chapter P01) the recommended value is 0.

On exit: IFAIL = 0 unless the routine detects an error (see Section 6).

### 6 Errors and Warnings

If on entry IFAIL = 0 or -1, explanatory error messages are output on the current error message unit (as defined by X04AAF).

Errors detected by the routine:

IFAIL = 1

 $\begin{array}{ll} {\rm On\ entry}, & {\rm M} < 10, \\ & {\rm or} \quad {\rm LIQ} < 2 \times {\rm M} + 1, \\ & {\rm or} \quad {\rm LRQ} < 10 \times {\rm M} + 7, \\ & {\rm or} \quad {\rm N} < 1. \end{array}$ 

#### IFAIL = 2

Values supplied in IQ or RQ appear to be invalid. Check that these arrays have not been corrupted between the calls to E01TGF and E01THF.

#### IFAIL = 3

At least one evaluation point lies outside the region of definition of the interpolant. At all such points the corresponding values in Q, QX, QY and QZ have been set to the largest machine representable number (see X02ALF).

# 7 Accuracy

Computational errors should be negligible in most practical situations.

## 8 Further Comments

The time taken for a call to E01THF will depend in general on the distribution of the data points. If X, Y and Z are approximately uniformly distributed, then the time taken should be only O(N). At worst O(MN) time will be required.

## 9 Example

See Section 9 of the document for E01TGF.