#### E02CBF – NAG Fortran Library Routine Document

**Note.** Before using this routine, please read the Users' Note for your implementation to check the interpretation of bold italicised terms and other implementation-dependent details.

### 1 Purpose

E02CBF evaluates a bivariate polynomial from the rectangular array of coefficients in its double Chebyshev-series representation.

# 2 Specification

```
SUBROUTINE E02CBF(MFIRST, MLAST, K, L, X, XMIN, XMAX, Y, YMIN,1YMAX, FF, A, NA, WORK, NWORK, IFAIL)INTEGERMFIRST, MLAST, K, L, NA, NWORK, IFAILrealX(MLAST), XMIN, XMAX, Y, YMIN, YMAX, FF(MLAST),1A(NA), WORK(NWORK)
```

# 3 Description

This subroutine evaluates a bivariate polynomial (represented in double Chebyshev form) of degree k in one variable,  $\bar{x}$ , and degree l in the other,  $\bar{y}$ . The range of both variables is -1 to +1. However, these normalised variables will usually have been derived (as when the polynomial has been computed by E02CAF, for example) from the user's original variables x and y by the transformations

$$\bar{x} = \frac{2x - (x_{\max} + x_{\min})}{(x_{\max} - x_{\min})}$$
 and  $\bar{y} = \frac{2y - (y_{\max} + y_{\min})}{(y_{\max} - y_{\min})}$ .

(Here  $x_{\min}$  and  $x_{\max}$  are the ends of the range of x which has been transformed to the range -1 to +1 of  $\bar{x}$ .  $y_{\min}$  and  $y_{\max}$  are correspondingly for y. See Section 8). For this reason, the subroutine has been designed to accept values of x and y rather than  $\bar{x}$  and  $\bar{y}$ , and so requires values of  $x_{\min}$ , etc. to be supplied by the user. In fact, for the sake of efficiency in appropriate cases, the routine evaluates the polynomial for a sequence of values of x, all associated with the same value of y.

The double Chebyshev-series can be written as

$$\sum_{i=0}^k \sum_{j=0}^l a_{ij} T_i(\bar{x}) T_j(\bar{y}),$$

where  $T_i(\bar{x})$  is the Chebyshev polynomial of the first kind of degree *i* and argument  $\bar{x}$ , and  $T_j(\bar{y})$  is similarly defined. However the standard convention, followed in this subroutine, is that coefficients in the above expression which have either *i* or *j* zero are written  $\frac{1}{2}a_{ij}$ , instead of simply  $a_{ij}$ , and the coefficient with both *i* and *j* zero is written  $\frac{1}{4}a_{0,0}$ .

The subroutine first forms  $c_i = \sum_{j=0}^{l} a_{ij}T_j(\bar{y})$ , with  $a_{i,0}$  replaced by  $\frac{1}{2}a_{i,0}$ , for each of  $i = 0, 1, \ldots, k$ . The value of the double series is then obtained for each value of x, by summing  $c_i \times T_i(\bar{x})$ , with  $c_0$  replaced by  $\frac{1}{2}c_0$ , over  $i = 0, 1, \ldots, k$ . The Clenshaw three term recurrence [1] with modifications due to Reinsch and Gentleman [2] is used to form the sums.

### 4 References

- [1] Clenshaw C W (1955) A note on the summation of Chebyshev series Math. Tables Aids Comput. 9 118–120
- [2] Gentleman W M (1969) An error analysis of Goertzel's (Watt's) method for computing Fourier coefficients Comput. J. 12 160–165

# **5** Parameters

5	Parameters	
1: 2:	MFIRST — INTEGER Inpu MLAST — INTEGER Inpu	
	On entry: the index of the first and last $x$ value in the array $x$ at which the evaluation is require respectively (see Section 8).	d
	Constraint: $MLAST \ge MFIRST$ .	
3: 4:	K — INTEGER Inpu L — INTEGER Inpu	
	On entry: the degree $k$ of $x$ and $l$ of $y$ , respectively, in the polynomial.	
	Constraint: K and $L \ge 0$ .	
5:	X(MLAST) - real array Input	ıt
	On entry: $X(i)$ , for $i = MFIRST, MFIRST + 1,, MLAST$ , must contain the x values at which the evaluation is required.	h
	Constraint: XMIN $\leq X(i) \leq XMAX$ , for all <i>i</i> .	
6: 7:	XMIN — realInputXMAX — realInput	
	On entry: the lower and upper ends, $x_{\min}$ and $x_{\max}$ , of the range of the variable x (see Section 3)	
	The values of XMIN and XMAX may depend on the value of $y$ (e.g., when the polynomial has bee derived using E02CAF).	n
	Constraint: $XMAX > XMIN$ .	
8:	Y - real	ut
	On entry: the value of the $y$ co-ordinate of all the points at which the evaluation is required.	
	Constraint: $YMIN \le Y \le YMAX$ .	
9: 10:	YMIN — real YMAX — real Inpu	
10.	On entry: the lower and upper ends, $y_{\min}$ and $y_{\max}$ , of the range of the variable $y$ (see Section 3)	
	Constraint: YMAX > YMIN.	
11:	FF(MLAST) - real array Output	ut
	On exit: $FF(i)$ gives the value of the polynomial at the point $(x_i, y)$ , for $i = MFIRST$ , MFIRST - 1,, MLAST.	+
12:	A(NA) - real array Input	ıt
	On artmy the Chebyshaw coefficients of the polynomial. The coefficient a defined according to the	

On entry: the Chebyshev coefficients of the polynomial. The coefficient  $a_{ij}$  defined according to the standard convention (see Section 3) must be in  $A(i \times (l+1) + j + 1)$ .

#### 13: NA — INTEGER

 $On\ entry:$  the dimension of the array A as declared in the (sub)program from which E02CBF is called.

Constraint: NA  $\geq$  (K + 1)  $\times$  (L + 1), the number of coefficients in a polynomial of the specified degree.

Input

15: NWORK — INTEGER

*On entry:* the dimension of the array WORK as declared in the (sub)program from which E02CBF is called.

Constraint: NWORK  $\geq K + 1$ .

**16:** IFAIL — INTEGER

On entry: IFAIL must be set to 0, -1 or 1. For users not familiar with this parameter (described in Chapter P01) the recommended value is 0.

On exit: IFAIL = 0 unless the routine detects an error (see Section 6).

# 6 Error Indicators and Warnings

Errors detected by the routine:

IFAIL = 1

```
 \begin{array}{ll} \text{On entry,} & \text{MFIRST} > \text{MLAST,} \\ & \text{or} & \text{K} < 0, \\ & \text{or} & \text{L} < 0, \\ & \text{or} & \text{NA} < (\text{K}+1) \times (\text{L}+1), \\ & \text{or} & \text{NWORK} < \text{K}+1. \end{array}
```

IFAIL = 2

On entry,  $YMIN \ge YMAX$ , or Y < YMIN, or Y > YMAX.

IFAIL = 3

```
On entry, XMIN \geq XMAX,
or X(i) < XMIN, or X(i) > XMAX, for some i = MFIRST, MFIRST + 1, ..., MLAST.
```

# 7 Accuracy

The method is numerically stable in the sense that the computed values of the polynomial are exact for a set of coefficients which differ from those supplied by only a modest multiple of *machine precision*.

# 8 Further Comments

The time taken by this routine is approximately proportional to  $(k + 1) \times (m + l + 1)$ , where m = MLAST - MFIRST + 1, the number of points at which the evaluation is required.

This subroutine is suitable for evaluating the polynomial surface fits produced by the subroutine E02CAF, which provides the *real* array A in the required form. For this use, the values of  $y_{\min}$  and  $y_{\max}$  supplied to the present subroutine must be the same as those supplied to E02CAF. The same applies to  $x_{\min}$  and  $x_{\max}$  if they are independent of y. If they vary with y, their values must be consistent with those supplied to E02CAF (see Section 8 of the document for E02CAF).

The parameters MFIRST and MLAST are intended to permit the selection of a segment of the array X which is to be associated with a particular value of y, when, for example, other segments of X are associated with other values of y. Such a case arises when, after using E02CAF to fit a set of data, the user wishes to evaluate the resulting polynomial at all the data values. In this case, if the parameters X, Y, MFIRST and MLAST of the present routine are set respectively (in terms of parameters of E02CAF)

E02CBF

Input/Output

to X,Y(S),  $1 + \sum_{i=1}^{S-1} M(i)$  and  $\sum_{i=1}^{S} M(i)$ , the routine will compute values of the polynomial surface at all data points which have Y(S) as their y co-ordinate (from which values the residuals of the fit may be derived).

# 9 Example

The example program reads data in the following order, using the notation of the parameter list above:

```
N K L
A(i), for i = 1, 2, ..., (K + 1) \times (L + 1)
YMIN YMAX
Y(i) M(i) XMIN(i) XMAX(i) X1(i) XM(i), for i = 1, 2, ..., N.
```

For each line Y = Y(i) the polynomial is evaluated at M(i) equispaced points between X1(i) and XM(i) inclusive.

#### 9.1 Program Text

**Note.** The listing of the example program presented below uses bold italicised terms to denote precision-dependent details. Please read the Users' Note for your implementation to check the interpretation of these terms. As explained in the Essential Introduction to this manual, the results produced may not be identical for all implementations.

```
*
     E02CBF Example Program Text.
     Mark 14 Revised. NAG Copyright 1989.
*
      .. Parameters ..
     INTEGER
                      MMAX, KMAX, NWORK, LMAX, NA
     PARAMETER
                      (MMAX=100,KMAX=9,NWORK=KMAX+1,LMAX=9,NA=(KMAX+1)
                       *(LMAX+1))
     +
      INTEGER
                       NIN, NOUT
     PARAMETER
                       (NIN=5,NOUT=6)
      .. Local Scalars ..
                       X1, XM, XMAX, XMIN, Y, YMAX, YMIN
      real
      INTEGER
                       I, IFAIL, J, K, L, M, N, NCOEF
      .. Local Arrays ..
                       A(NA), FF(MMAX), WORK(NWORK), X(MMAX)
     real
      .. External Subroutines ..
      EXTERNAL
                       E02CBF
      .. Intrinsic Functions ..
      INTRINSIC
                       real
      .. Executable Statements ..
      WRITE (NOUT,*) 'E02CBF Example Program Results'
     Skip heading in data file
     READ (NIN,*)
  20 READ (NIN,*,END=100) N, K, L
      IF (K.LE.KMAX .AND. L.LE.LMAX) THEN
        NCOEF = (K+1)*(L+1)
        READ (NIN,*) (A(I),I=1,NCOEF)
        READ (NIN,*) YMIN, YMAX
        DO 80 I = 1, N
            READ (NIN,*) Y, M, XMIN, XMAX, X1, XM
            IF (M.LE.MMAX) THEN
               DO 40 J = 1, M
                  X(J) = X1 + ((XM-X1)*real(J-1))/real(M-1)
               CONTINUE
   40
               IFAIL = 0
               CALL E02CBF(1,M,K,L,X,XMIN,XMAX,Y,YMIN,YMAX,FF,A,NA,WORK,
                           NWORK, IFAIL)
     +
```

```
*
              WRITE (NOUT,*)
              WRITE (NOUT, 99999) 'Y = ', Y
              WRITE (NOUT,*)
              WRITE (NOUT,*) ' I X(I) Poly(X(I),Y)'
              DO 60 J = 1, M
                 WRITE (NOUT,99998) J, X(J), FF(J)
  60
              CONTINUE
           END IF
  80
        CONTINUE
        GO TO 20
     END IF
 100 STOP
*
99999 FORMAT (1X,A,e13.4)
99998 FORMAT (1X,I3,1P,2e13.4)
     END
```

#### 9.2 Program Data

E02CBF	Example 1	Progr	am Data			
3	32					
15.348	20					
5.150	73					
0.1014	40					
1.147	19					
0.144	19					
-0.1040	64					
0.0490	01					
-0.003	14					
-0.0069	99					
0.001	53					
-0.0003	33					
-0.000	22					
0.0		4.0				
1.0		9	0.1	4.5	0.5	4.5
1.5		8	0.225	4.25	0.5	4.0
2.0		8	0.4	4.0	0.5	4.0

#### 9.3 Program Results

E02CBF Example Program Results

```
Y = 0.1000E+01
```

Ι	X(I)	Poly(X(I),Y)
1	5.0000E-01	2.0812E+00
2	1.0000E+00	2.1888E+00
3	1.5000E+00	2.3018E+00
4	2.0000E+00	2.4204E+00
5	2.5000E+00	2.5450E+00
6	3.0000E+00	2.6758E+00
7	3.5000E+00	2.8131E+00
8	4.0000E+00	2.9572E+00
9	4.5000E+00	3.1084E+00

Y =	0.1500E+01	
I	X(I)	Poly(X(I),Y)
1	5.0000E-01	2.6211E+00
2	1.0000E+00	2.7553E+00
3	1.5000E+00	2.8963E+00
4	2.0000E+00	3.0444E+00
5	2.5000E+00	3.2002E+00
6	3.0000E+00	3.3639E+00
7	3.5000E+00	3.5359E+00
8	4.0000E+00	3.7166E+00
Y =	0.2000E+01	
Y = I	0.2000E+01 X(I)	Poly(X(I),Y)
-		Poly(X(I),Y) 3.1700E+00
I	X(I)	•
I 1	X(I) 5.0000E-01	3.1700E+00
I 1 2	X(I) 5.0000E-01 1.0000E+00	3.1700E+00 3.3315E+00
I 1 2 3	X(I) 5.0000E-01 1.0000E+00 1.5000E+00	3.1700E+00 3.3315E+00 3.5015E+00
I 1 2 3 4	X(I) 5.0000E-01 1.0000E+00 1.5000E+00 2.0000E+00 2.5000E+00	3.1700E+00 3.3315E+00 3.5015E+00 3.6806E+00
I 1 2 3 4 5	X(I) 5.0000E-01 1.0000E+00 1.5000E+00 2.0000E+00 2.5000E+00	3.1700E+00 3.3315E+00 3.5015E+00 3.6806E+00 3.8692E+00 4.0678E+00
I 1 2 3 4 5 6	X(I) 5.0000E-01 1.0000E+00 1.5000E+00 2.0000E+00 3.0000E+00	3.1700E+00 3.3315E+00 3.5015E+00 3.6806E+00 3.8692E+00 4.0678E+00