## F07HVF (CPBRFS/ZPBRFS) - NAG Fortran Library Routine Document

Note. Before using this routine, please read the Users' Note for your implementation to check the interpretation of bold italicised terms and other implementation-dependent details.

# 1 Purpose

F07HVF (CPBRFS/ZPBRFS) returns error bounds for the solution of a complex Hermitian positive-definite band system of linear equations with multiple right-hand sides, AX = B. It improves the solution by iterative refinement, in order to reduce the backward error as much as possible.

# 2 Specification

```
SUBROUTINE FO7HVF(UPLO, N, KD, NRHS, AB, LDAB, AFB, LDAFB, B, LDB, X, LDX, FERR, BERR, WORK, RWORK, INFO)

ENTRY cpbrfs(UPLO, N, KD, NRHS, AB, LDAB, AFB, LDAFB, B, LDB, X, LDX, FERR, BERR, WORK, RWORK, INFO)

INTEGER N, KD, NRHS, LDAB, LDAFB, LDB, LDX, INFO real FERR(*), BERR(*), RWORK(*)

complex AB(LDAB,*), AFB(LDAFB,*), B(LDB,*), X(LDX,*), 1

WORK(*)

CHARACTER*1 UPLO
```

The ENTRY statement enables the routine to be called by its LAPACK name.

# 3 Description

This routine returns the backward errors and estimated bounds on the forward errors for the solution of a complex Hermitian positive-definite band system of linear equations with multiple right-hand sides AX = B. The routine handles each right-hand side vector (stored as a column of the matrix B) independently, so we describe the function of the routine in terms of a single right-hand side b and solution x.

Given a computed solution x, the routine computes the *component-wise backward error*  $\beta$ . This is the size of the smallest relative perturbation in each element of A and b such that x is the exact solution of a perturbed system

$$(A + \delta A)x = b + \delta b$$
  $|\delta a_{ij}| \le \beta |a_{ij}|$  and  $|\delta b_i| \le \beta |b_i|$ .

Then the routine estimates a bound for the *component-wise forward error* in the computed solution, defined by:

$$\max_i |x_i - \hat{x}_i| / \max_i |x_i|$$

where  $\hat{x}$  is the true solution.

For details of the method, see the Chapter Introduction.

## 4 References

[1] Golub G H and van Loan C F (1996) Matrix Computations Johns Hopkins University Press (3rd Edition), Baltimore

## 5 Parameters

1: UPLO — CHARACTER\*1

Input

On entry: indicates whether the upper or lower triangular part of A is stored and how A has been factorized, as follows:

if UPLO = 'U', then the upper triangular part of A is stored and A is factorized as  $U^HU$ , where U is upper triangular;

if UPLO = 'L', then the lower triangular part of A is stored and A is factorized as  $LL^H$ , where L is lower triangular.

Constraint: UPLO = 'U' or 'L'.

#### **2**: N — INTEGER

Input

On entry: n, the order of the matrix A.

Constraint:  $N \geq 0$ .

## 3: KD — INTEGER

Input

On entry: k, the number of super-diagonals or sub-diagonals of the matrix A.

Constraint:  $KD \geq 0$ .

#### 4: NRHS — INTEGER

Input

On entry: r, the number of right-hand sides.

Constraint: NRHS  $\geq 0$ .

## 5: AB(LDAB,\*) — complex array

Input

**Note:** the second dimension of the array AB must be at least max(1,N).

On entry: the n by n original Hermitian positive-definite band matrix A as supplied to F07HRF (CPBTRF/ZPBTRF).

#### **6:** LDAB — INTEGER

Input

On entry: the first dimension of the array AB as declared in the (sub)program from which F07HVF (CPBRFS/ZPBRFS) is called.

Constraint: LDAB  $\geq$  KD + 1.

### 7: AFB(LDAFB,\*) — complex array

Input

Note: the second dimension of the array AFB must be at least  $\max(1,N)$ .

On entry: the Cholesky factor of A, as returned by F07HRF (CPBTRF/ZPBTRF).

#### 8: LDAFB — INTEGER

Input

On entry: the first dimension of the array AFB as declared in the (sub)program from which F07HVF (CPBRFS/ZPBRFS) is called.

Constraint: LDAFB  $\geq$  KD + 1.

### 9: B(LDB,\*) - complex array

Input

**Note:** the second dimension of the array B must be at least max(1,NRHS).

On entry: the n by r right-hand side matrix B.

### 10: LDB — INTEGER

Input

On entry: the first dimension of the array B as declared in the (sub)program from which F07HVF (CPBRFS/ZPBRFS) is called.

Constraint: LDB  $\geq \max(1,N)$ .

### 11: X(LDX,\*) — complex array

Input/Output

**Note:** the second dimension of the array X must be at least max(1,NRHS).

On entry: the n by r solution matrix X, as returned by F07HSF (CPBTRS/ZPBTRS).

On exit: the improved solution matrix X.

12: LDX — INTEGER Input

On entry: the first dimension of the array X as declared in the (sub)program from which F07HVF (CPBRFS/ZPBRFS) is called.

Constraint: LDX  $\geq \max(1,N)$ .

13: FERR(\*) — real array

Output

Note: the dimension of the array FERR must be at least  $\max(1, NRHS)$ .

On exit: FERR(j) contains an estimated error bound for the jth solution vector, that is, the jth column of X, for j = 1, 2, ..., r.

14: BERR(\*) — real array

Output

**Note:** the dimension of the array BERR must be at least max(1,NRHS).

On exit: BERR(j) contains the component-wise backward error bound  $\beta$  for the jth solution vector, that is, the jth column of X, for j = 1, 2, ..., r.

15: WORK(\*) — complex array

Workspace

**Note:** the dimension of the array WORK must be at least max(1,2\*N).

16: RWORK(\*) — real array

Workspace

**Note:** the dimension of the array RWORK must be at least max(1,N).

17: INFO — INTEGER

Output

On exit: INFO = 0 unless the routine detects an error (see Section 6).

# 6 Error Indicators and Warnings

INFO < 0

If INFO = -i, the *i*th parameter had an illegal value. An explanatory message is output, and execution of the program is terminated.

# 7 Accuracy

The bounds returned in FERR are not rigorous, because they are estimated, not computed exactly; but in practice they almost always overestimate the actual error.

### 8 Further Comments

For each right-hand side, computation of the backward error involves a minimum of 32nk real floating-point operations. Each step of iterative refinement involves an additional 48nk real operations. This assumes  $n \gg k$ . At most 5 steps of iterative refinement are performed, but usually only 1 or 2 steps are required.

Estimating the forward error involves solving a number of systems of linear equations of the form Ax = b; the number is usually 5 and never more than 11. Each solution involves approximately 16nk real operations.

The real analogue of this routine is F07HHF (SPBRFS/DPBRFS).

# 9 Example

To solve the system of equations AX = B using iterative refinement and to compute the forward and backward error bounds, where

$$A = \begin{pmatrix} 9.39 + 0.00i & 1.08 - 1.73i & 0.00 + 0.00i & 0.00 + 0.00i \\ 1.08 + 1.73i & 1.69 + 0.00i & -0.04 + 0.29i & 0.00 + 0.00i \\ 0.00 + 0.00i & -0.04 - 0.29i & 2.65 + 0.00i & -0.33 + 2.24i \\ 0.00 + 0.00i & 0.00 + 0.00i & -0.33 - 2.24i & 2.17 + 0.00i \end{pmatrix}$$

and

$$B = \begin{pmatrix} -12.42 + 68.42i & 54.30 - 56.56i \\ -9.93 + & 0.88i & 18.32 + & 4.76i \\ -27.30 - & 0.01i & -4.40 + & 9.97i \\ 5.31 + 23.63i & 9.43 + & 1.41i \end{pmatrix}.$$

Here A is Hermitian positive-definite, and is treated as a band matrix, which must first be factorized by F07HRF (CPBTRF/ZPBTRF).

## 9.1 Program Text

**Note.** The listing of the example program presented below uses bold italicised terms to denote precision-dependent details. Please read the Users' Note for your implementation to check the interpretation of these terms. As explained in the Essential Introduction to this manual, the results produced may not be identical for all implementations.

```
FO7HVF Example Program Text
Mark 15 Release. NAG Copyright 1991.
.. Parameters ..
INTEGER
              NIN, NOUT
PARAMETER
               (NIN=5,NOUT=6)
               ZERO
complex
PARAMETER
               (ZERO=(0.0e0,0.0e0))
INTEGER
               NMAX, NRHMAX, KDMAX, LDAB, LDAFB, LDB, LDX
PARAMETER
               (NMAX=8, NRHMAX=NMAX, KDMAX=8, LDAB=KDMAX+1,
                 LDAFB=KDMAX+1,LDB=NMAX,LDX=NMAX)
.. Local Scalars ..
               I, IFAIL, INFO, J, KD, N, NRHS
INTEGER
CHARACTER
                UPLO
.. Local Arrays ..
complex
                AB(LDAB, NMAX), AFB(LDAFB, NMAX), B(LDB, NRHMAX),
                 WORK(2*NMAX), X(LDX,NMAX)
                 BERR(NRHMAX), FERR(NRHMAX), RWORK(NMAX)
real
CHARACTER
                CLABS(1), RLABS(1)
.. External Subroutines ..
EXTERNAL
                cpbrfs, cpbtrf, cpbtrs, F06TFF, F06THF, X04DBF
.. Intrinsic Functions ..
INTRINSIC
                MAX, MIN
.. Executable Statements ..
WRITE (NOUT,*) 'FO7HVF Example Program Results'
Skip heading in data file
READ (NIN,*)
READ (NIN,*) N, KD, NRHS
IF (N.LE.NMAX .AND. KD.LE.KDMAX .AND. NRHS.LE.NRHMAX) THEN
   Set A to zero to avoid referencing uninitialized elements
   CALL FO6THF ('General', KD+1, N, ZERO, ZERO, AB, LDAB)
```

```
Read A and B from data file, and copy A to AFB and B to X
         READ (NIN,*) UPLO
         IF (UPLO.EQ.'U') THEN
            DO 20 I = 1, N
               READ (NIN,*) (AB(KD+1+I-J,J),J=I,MIN(N,I+KD))
   20
            CONTINUE
         ELSE IF (UPLO.EQ.'L') THEN
            DO 40 I = 1, N
               READ (NIN,*) (AB(1+I-J,J),J=MAX(1,I-KD),I)
   40
            CONTINUE
         END IF
         READ (NIN,*) ((B(I,J),J=1,NRHS),I=1,N)
         CALL F06TFF('General',KD+1,N,AB,LDAB,AFB,LDAFB)
         CALL F06TFF('General',N,NRHS,B,LDB,X,LDX)
         Factorize A in the array AFB
         CALL cpbtrf(UPLO, N, KD, AFB, LDAFB, INFO)
         WRITE (NOUT,*)
         IF (INFO.EQ.O) THEN
            Compute solution in the array X
            CALL cpbtrs (UPLO,N,KD,NRHS,AFB,LDAFB,X,LDX,INFO)
            Improve solution, and compute backward errors and
            estimated bounds on the forward errors
            CALL cpbrfs (UPLO, N, KD, NRHS, AB, LDAB, AFB, LDAFB, B, LDB, X, LDX,
                         FERR, BERR, WORK, RWORK, INFO)
            Print solution
            IFAIL = 0
            CALL XO4DBF('General',' ',N,NRHS,X,LDX,'Bracketed','F7.4',
                         'Solution(s)', 'Integer', RLABS, 'Integer', CLABS,
                         80,0,IFAIL)
            WRITE (NOUT, *)
            WRITE (NOUT,*) 'Backward errors (machine-dependent)'
            WRITE (NOUT, 99999) (BERR(J), J=1, NRHS)
            WRITE (NOUT, *)
              'Estimated forward error bounds (machine-dependent)'
            WRITE (NOUT, 99999) (FERR(J), J=1, NRHS)
         ELSE
            WRITE (NOUT,*) 'A is not positive-definite'
         END IF
      END IF
      STOP
99999 FORMAT ((5X,1P,4(e11.1,7X)))
      END
```

## 9.2 Program Data

## 9.3 Program Results

FO7HVF Example Program Results

3.2E-14

```
Solution(s)
```

```
1 2
1 (-1.0000, 8.0000) (5.0000,-6.0000)
2 (2.0000,-3.0000) (2.0000, 3.0000)
3 (-4.0000,-5.0000) (-8.0000, 4.0000)
4 (7.0000, 6.0000) (-1.0000,-7.0000)

Backward errors (machine-dependent)
8.2E-17 8.3E-17

Estimated forward error bounds (machine-dependent)
```

2.9E-14