### F07VEF (STBTRS/DTBTRS) - NAG Fortran Library Routine Document

**Note.** Before using this routine, please read the Users' Note for your implementation to check the interpretation of bold italicised terms and other implementation-dependent details.

# 1 Purpose

F07VEF (STBTRS/DTBTRS) solves a real triangular band system of linear equations with multiple right-hand sides, AX = B or  $A^T X = B$ .

# 2 Specification

```
SUBROUTINE FO7VEF(UPLO, TRANS, DIAG, N, KD, NRHS, AB, LDAB, B,1LDB, INFO)ENTRYstbtrs(UPLO, TRANS, DIAG, N, KD, NRHS, AB, LDAB, B,1LDB, INFO)INTEGERN, KD, NRHS, LDAB, LDB, INFOrealAB(LDAB,*), B(LDB,*)CHARACTER*1UPLO, TRANS, DIAG
```

The ENTRY statement enables the routine to be called by its LAPACK name.

# 3 Description

This routine solves a real triangular band system of linear equations AX = B or  $A^T X = B$ .

### 4 References

- Golub G H and van Loan C F (1996) Matrix Computations Johns Hopkins University Press (3rd Edition), Baltimore
- Higham N J (1989) The accuracy of solutions to triangular systems SIAM J. Numer. Anal. 26 1252–1265

### **5** Parameters

1: UPLO — CHARACTER\*1

 $On \ entry:$  indicates whether A is upper or lower triangular as follows:

if UPLO = 'U', then A is upper triangular; if UPLO = 'L', then A is lower triangular.

Constraint: UPLO = 'U' or 'L'.

**2:** TRANS — CHARACTER\*1

On entry: indicates the form of the equations as follows:

if TRANS = 'N', then the equations are of the form AX = B; if TRANS = 'T' or 'C', then the equations are of the form  $A^T X = B$ .

Constraint: TRANS = 'N', 'T' or 'C'.

Input

Input

#### **F07VEF (STBTRS/DTBTRS)**

#### **3:** DIAG — CHARACTER\*1

On entry: indicates whether A is a non-unit or unit triangular matrix as follows:

if DIAG = N', then A is a non-unit triangular matrix;

if DIAG = 'U', then A is a unit triangular matrix; the diagonal elements are not referenced and are assumed to be 1.

Constraint: DIAG = 'N' or 'U'.

4: N — INTEGER

On entry: n, the order of the matrix A.

Constraint:  $N \ge 0$ .

#### 5: KD — INTEGER

On entry: k, the number of super-diagonals of the matrix A if UPLO = 'U' or the number of sub-diagonals if UPLO = 'L'.

Constraint:  $KD \ge 0$ .

#### 6: NRHS — INTEGER

On entry: r, the number of right-hand sides.

Constraint: NRHS  $\geq 0$ .

#### 7: AB(LDAB,\*) — *real* array

Note: the second dimension of the array AB must be at least  $\max(1,N)$ .

On entry: the n by n triangular band matrix A, stored in rows 1 to (k+1). More precisely, if UPLO = 'U', the elements of the upper triangle of A within the band must be stored with element  $a_{ij}$  in AB(k+1+i-j,j) for  $max(1,j-k) \le i \le j$ ; if UPLO = 'L', the elements of the lower triangle of A within the band must be stored with element  $a_{ij}$  in AB(1+i-j,j) for  $j \le i \le min(n,j+k)$ . If DIAG = 'U', the diagonal elements are not referenced and are assumed to be 1.

#### 8: LDAB — INTEGER

*On entry:* the first dimension of the array AB as declared in the (sub)program from which F07VEF (STBTRS/DTBTRS) is called.

Constraint: LDAB  $\geq$  KD + 1.

9: B(LDB,\*) - real array

Note: the second dimension of the array B must be at least  $\max(1,\!\mathrm{NRHS})$  .

On entry: the n by r right-hand side matrix B.

On exit: the n by r solution matrix X.

**10:** LDB — INTEGER

*On entry:* the first dimension of the array B as declared in the (sub)program from which F07VEF (STBTRS/DTBTRS) is called.

Constraint: LDB  $\geq \max(1,N)$ .

**11:** INFO — INTEGER

On exit: INFO = 0 unless the routine detects an error (see Section 6).

Output

Input

Input

Input

Input

Input

Input

Input/Output

### 6 Error Indicators and Warnings

INFO < 0

If INFO = -i, the *i*th parameter had an illegal value. An explanatory message is output, and execution of the program is terminated.

INFO > 0

If INFO = i,  $a_{ii}$  is zero and the matrix A is singular.

## 7 Accuracy

The solutions of triangular systems of equations are usually computed to high accuracy. See Higham [2].

For each right-hand side vector b, the computed solution x is the exact solution of a perturbed system of equations (A + E)x = b, where

 $|E| \le c(k)\epsilon|A|,$ 

c(k) is a modest linear function of k, and  $\epsilon$  is the *machine precision*.

If  $\hat{x}$  is the true solution, then the computed solution x satisfies a forward error bound of the form

$$\frac{\|x - \hat{x}\|_{\infty}}{\|x\|_{\infty}} \le c(k) \text{cond}(A, x)\epsilon, \text{ provided } c(k) \text{cond}(A, x)\epsilon < 1,$$

where  $\operatorname{cond}(A, x) = \| |A^{-1}| |A| |x| \|_{\infty} / \|x\|_{\infty}.$ 

Note that  $\operatorname{cond}(A, x) \leq \operatorname{cond}(A) = ||A^{-1}||A|||_{\infty} \leq \kappa_{\infty}(A)$ ;  $\operatorname{cond}(A, x)$  can be much smaller than  $\operatorname{cond}(A)$  and it is also possible for  $\operatorname{cond}(A^T)$  to be much larger (or smaller) than  $\operatorname{cond}(A)$ .

Forward and backward error bounds can be computed by calling F07VHF (STBRFS/DTBRFS), and an estimate for  $\kappa_{\infty}(A)$  can be obtained by calling F07VGF (STBCON/DTBCON) with NORM = 'I'.

# 8 Further Comments

The total number of floating-point operations is approximately 2nkr if  $k \ll n.$ 

The complex analogue of this routine is F07VSF (CTBTRS/ZTBTRS).

### 9 Example

To solve the system of equations AX = B, where

$$A = \begin{pmatrix} -4.16 & 0.00 & 0.00 & 0.00 \\ -2.25 & 4.78 & 0.00 & 0.00 \\ 0.00 & 5.86 & 6.32 & 0.00 \\ 0.00 & 0.00 & -4.82 & 0.16 \end{pmatrix} \text{ and } B = \begin{pmatrix} -16.64 & -4.16 \\ -13.78 & -16.59 \\ 13.10 & -4.94 \\ -14.14 & -9.96 \end{pmatrix}.$$

Here A is treated as a lower triangular band matrix with 1 sub-diagonal.

#### 9.1 Program Text

**Note.** The listing of the example program presented below uses bold italicised terms to denote precision-dependent details. Please read the Users' Note for your implementation to check the interpretation of these terms. As explained in the Essential Introduction to this manual, the results produced may not be identical for all implementations.

- \* F07VEF Example Program Text
- \* Mark 15 Release. NAG Copyright 1991.

*	Parameters	
	INTEGER	NIN, NOUT
	PARAMETER	(NIN=5,NOUT=6)
	INTEGER	NMAX, KDMAX, LDAB, NRHMAX, LDB
	PARAMETER	(NMAX=8,KDMAX=NMAX,LDAB=KDMAX+1,NRHMAX=NMAX,

```
+ LDB=NMAX)
CHARACTER TRANS, DIAG
PARAMETER (TRANS='N',DIAG='N')
     +
      .. Local Scalars ..
*
     INTEGER I, IFAIL, INFO, J, KD, N, NRHS
                  UPLO
     CHARACTER
     .. Local Arrays ..
*
                      AB(LDAB,NMAX), B(LDB,NRHMAX)
     real
     .. External Subroutines ..
*
     EXTERNAL stbtrs, X04CAF
     .. Intrinsic Functions ..
     INTRINSIC MAX, MIN
     .. Executable Statements ..
     WRITE (NOUT,*) 'FO7VEF Example Program Results'
     Skip heading in data file
*
     READ (NIN,*)
     READ (NIN,*) N, KD, NRHS
     IF (N.LE.NMAX .AND. KD.LE.KDMAX .AND. NRHS.LE.NRHMAX) THEN
         Read A and B from data file
*
*
         READ (NIN,*) UPLO
         IF (UPLO.EQ.'U') THEN
            DO 20 I = 1, N
               READ (NIN,*) (AB(KD+1+I-J,J),J=I,MIN(N,I+KD))
  20
            CONTINUE
         ELSE IF (UPLO.EQ.'L') THEN
            DO 40 I = 1, N
               READ (NIN,*) (AB(1+I-J,J),J=MAX(1,I-KD),I)
  40
            CONTINUE
         END IF
         READ (NIN,*) ((B(I,J),J=1,NRHS),I=1,N)
*
         Compute solution
*
*
         CALL stbtrs(UPLO, TRANS, DIAG, N, KD, NRHS, AB, LDAB, B, LDB, INFO)
*
         Print solution
*
         WRITE (NOUT,*)
         IF (INFO.EQ.O) THEN
            IFAIL = 0
            CALL X04CAF('General',' ',N,NRHS,B,LDB,'Solution(s)',IFAIL)
         ELSE
            WRITE (NOUT, *) 'A is singular'
         END IF
     END IF
     STOP
*
     END
```

### 9.2 Program Data

```
F07VEF Example Program Data

4 1 2 :Values of N, KD and NRHS

'L' :Value of UPLO

-4.16

-2.25 4.78

5.86 6.32

-4.82 0.16 :End of matrix A

-16.64 -4.16

-13.78 -16.59

13.10 -4.94

-14.14 -9.96 :End of matrix B
```

### 9.3 Program Results

FO7VEF Example Program Results

Solution(s)

	1	2
1	4.0000	1.0000
2	-1.0000	-3.0000
3	3.0000	2.0000
4	2.0000	-2.0000